

CS660/CS661 Spreader Controller

Installation Information

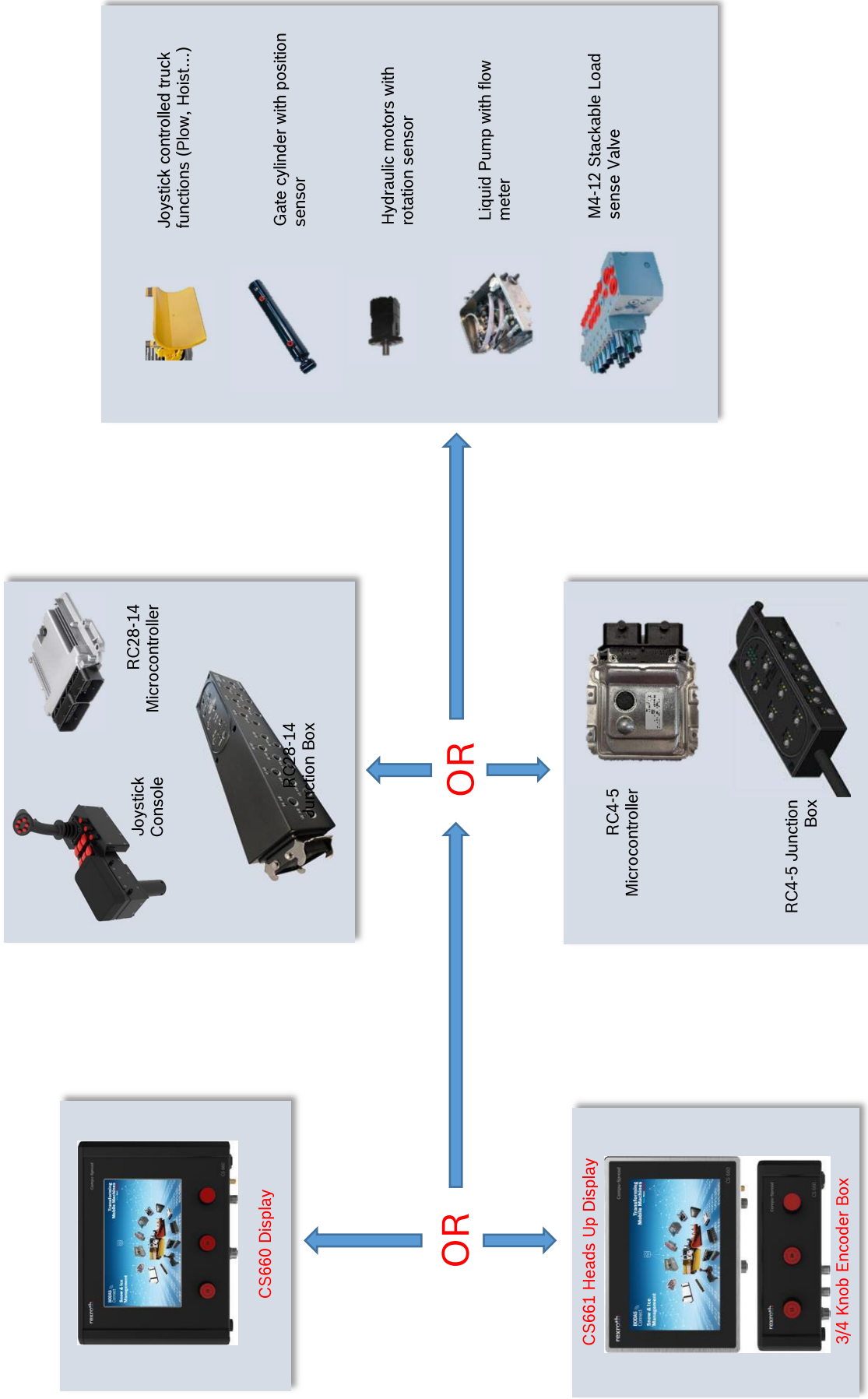


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1 System Components

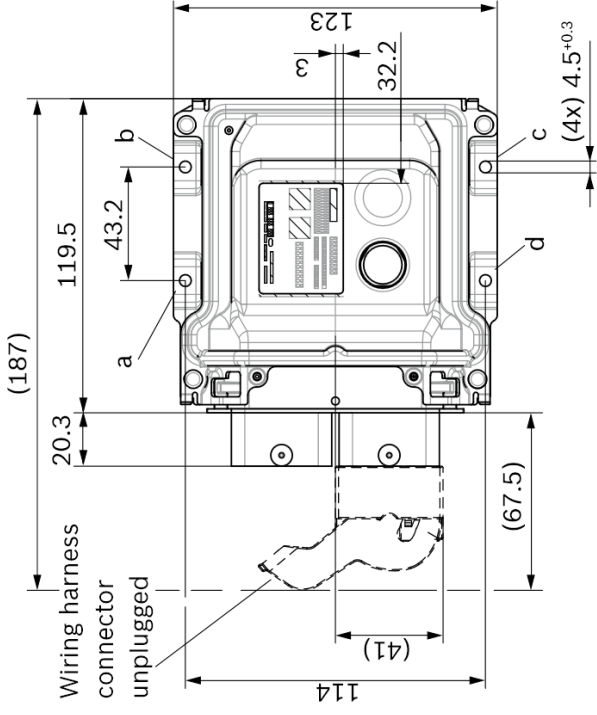


2 Mounting & Dimensions

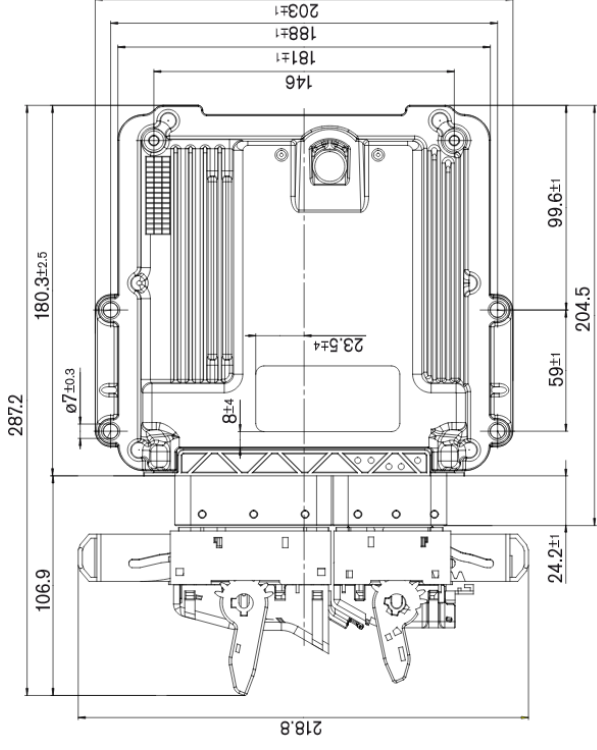
2.1 Microcontroller

1. The microcontroller(s) can be mounted horizontal or with the connectors oriented to the bottom. The controller cannot be mounted with the connectors facing upwards.
2. The mounting surface must be flat and all four bracket holes used.
3. Sufficient space must be allowed for the mating and un-mating of the connectors.
4. As the controller is directly connected to it's junction box, mounting both parts must be considered at the same time.

RC4-5



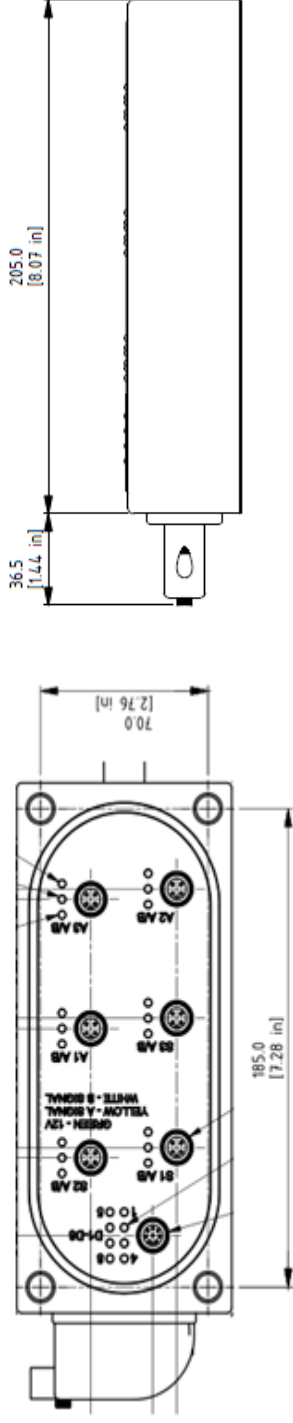
RC28-14



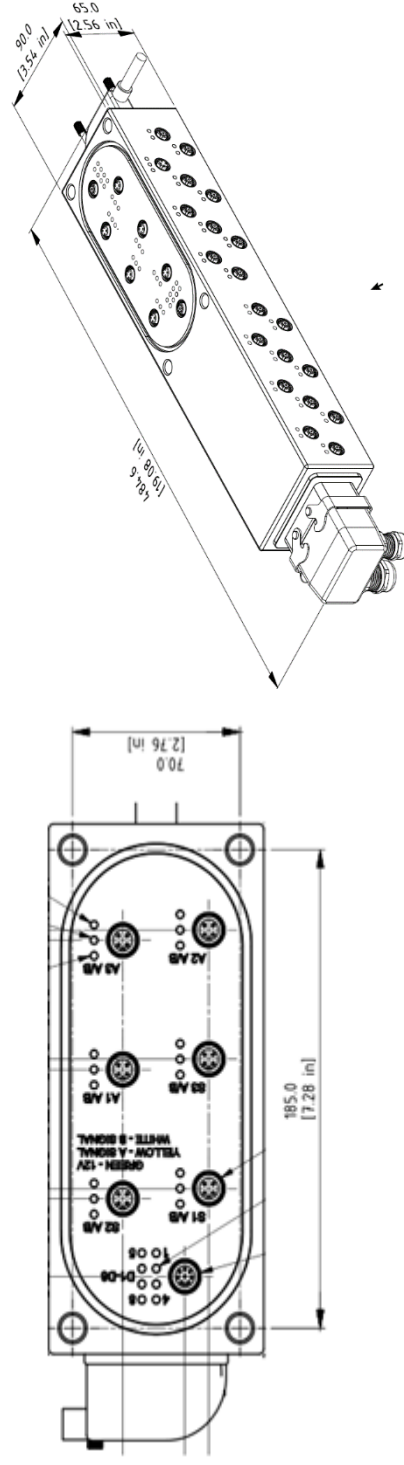
2.2 Junction Box

1. The junction box is designed to be mounted inside of an enclosure with a hole to accommodate the connection of sensors to outside devices.
2. The entire seal must make contact with the enclosure to prevent water and contaminants from entering the enclosure.

RC4-5 Junction Box

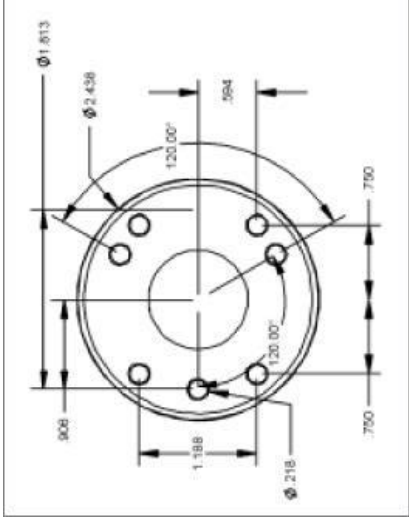
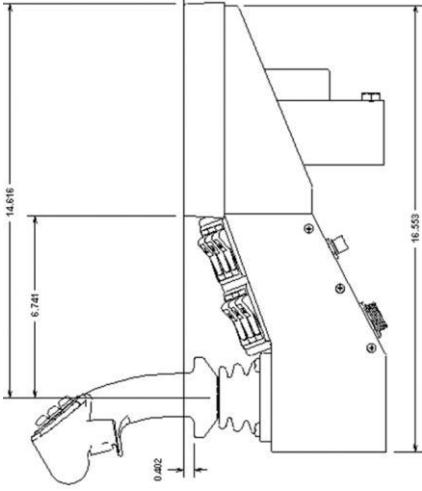


RC28-14 Junction Box



2.3 Display, Encoder Box & Joystick

1. Both 660 and 661 displays utilize a ball mount where 4 holes of the flange must be secured. (See hole array.)
2. A similar ball mount is used when the display is coupled to the armrest – one long arm and one short.
3. The joystick armrest console utilizes a tube mount that slips over 1-7/8" O/D pedestal tubing.
4. The tube mount can slide forward and back 1.7" to optimize the armrest position. (Loosen the ¼-20 nuts.)
5. The ratchet clamp can be used to lock the rotation of the tube and bracket.
6. See the "Installation Notes" section for additional recommendations.



3 Connector Details

3.1 Microcontroller Connection

1. Pull locking lever away from the cable end of the connector
2. Partially insert connector into socket and ensure the 2 coding posts align into housing.
3. Push locking lever in opposite direction and the connector will fully insert and lock itself.
4. To remove, pull the locking lever away from the cable side of the connector. It will un-mate.



3.2 Solenoid Connection

1. Press valve cable end onto solenoid connector



2. Press metal retainer to un-mate



4 Cable Connections

4.1 CS660 Display

1 Connect the CANBUS EXTENSION from CAN connector on the display to the CAN1 connector on the junction box.



- 2 Connect all sensor cables such as conveyor speed, ground speed from the sensors to the correct connector on the junction box.
- 3 Connect all valve splitter cables from the junction box to the proper solenoids on the hydraulic valve assembly

4.2 CS661 Heads Up Display with Encoder Box

- 1 Connect from CAN connector on the display to one of the leads on the CAN splitter cable.
- 2 Connect the other lead of the CAN splitter cable to the CAN1 connector on the encoder box. The encoder box may be attached to the joystick console. See OSD for details.
- 3 Connect the other end of the CAN splitter cable to CAN1 connector on the junction box
- 4 Connect all sensor cables including ground speed to the correct connector on the junction box.
- 5 Connect all valve splitter cables from the junction box to the proper solenoids on the hydraulic valve assembly

NOTE: INLINE SENSOR NETWORK(PN:R987376742) NEEDS TO BE INSTALLED FOR SENSORS REQUIRING A PULL UP RESISTOR , SUCH AS WHITE MOTOR TYPES.

5 Installation Notes

5.1 Step 1

Unpack all the supplied parts and check the packing list for completeness.

5.2 Step 2

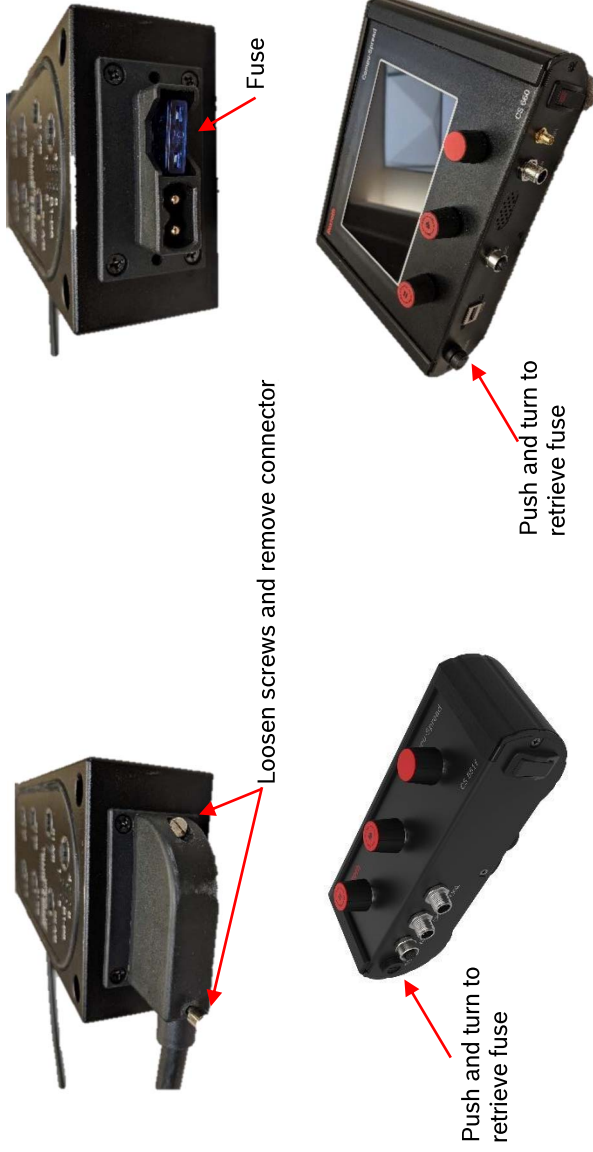
Untie and layout all the cables supplied, to ensure proper lengths.

Note: Electromagnetic devices such as relays, magnetic switches and solenoids, can generate large negative voltage spikes. These large spikes are introduced into the vehicle's electrical system and may adversely affect all electronic devices including engine computers. It is strongly recommended that these electromagnetic devices be electrically suppressed. See warnings and instructions in Body Builder manuals.

1. Connect the junction box power and the ground wire using a dedicated circuit only. (Recommend to connect to the ignition switch)
2. Ensure wiring for transmission devices such as radios, etc. are not attached to the controller or bundled with the controller wiring. And a sufficiently large distance to radio systems must be maintained.
3. Make sure all mounting posts are properly grounded; a direct ground wire to the negative battery post is recommended. Floor mats and undercoating will interfere with proper grounding.
4. Disconnect the battery terminals before welding on a vehicle with electronic equipment.
5. Disconnect the negative battery terminal when wiring electronic devices.
6. Mount the consoles so that they do not interfere with vehicle controls or obstruct visibility.
7. Mount microcontrollers so that oil and salt spray do not contact the housing.
8. Route cables so that they will not be abused, damaged or immersed in oil.
9. When routing cables through metal opening, always use grommets to prevent cable damage.

10. When running wires around a dump box pivot point, ensure no connectors can be separated when the hoist is activated.
11. Tie cables clear of all moving parts like drive-axles or conveyor chains.
12. Observe the cable labeling (under the clear cover) for the proper termination of inputs and outputs.
13. Use dielectric grease on all external cable connections and pins to ensure proper corrosion protection.
14. Thoroughly clean all power and ground terminals before connecting power harness.
15. Stand clear of any hydraulic functions when first powering up the system
16. DO NOT drill holes in any of the enclosures.
17. DO NOT re-wire any of the consoles or cable harnesses.
18. DO NOT weld on the vehicle without completely disconnecting all electronic consoles.

5.3 Fuses



Replace fuse with appropriate rating:			
RC4-5 Junction Box	15A	CS660 Console	2.5A
RC28-14 Junction Box	30A	CS550 Encoder Box	2.5A

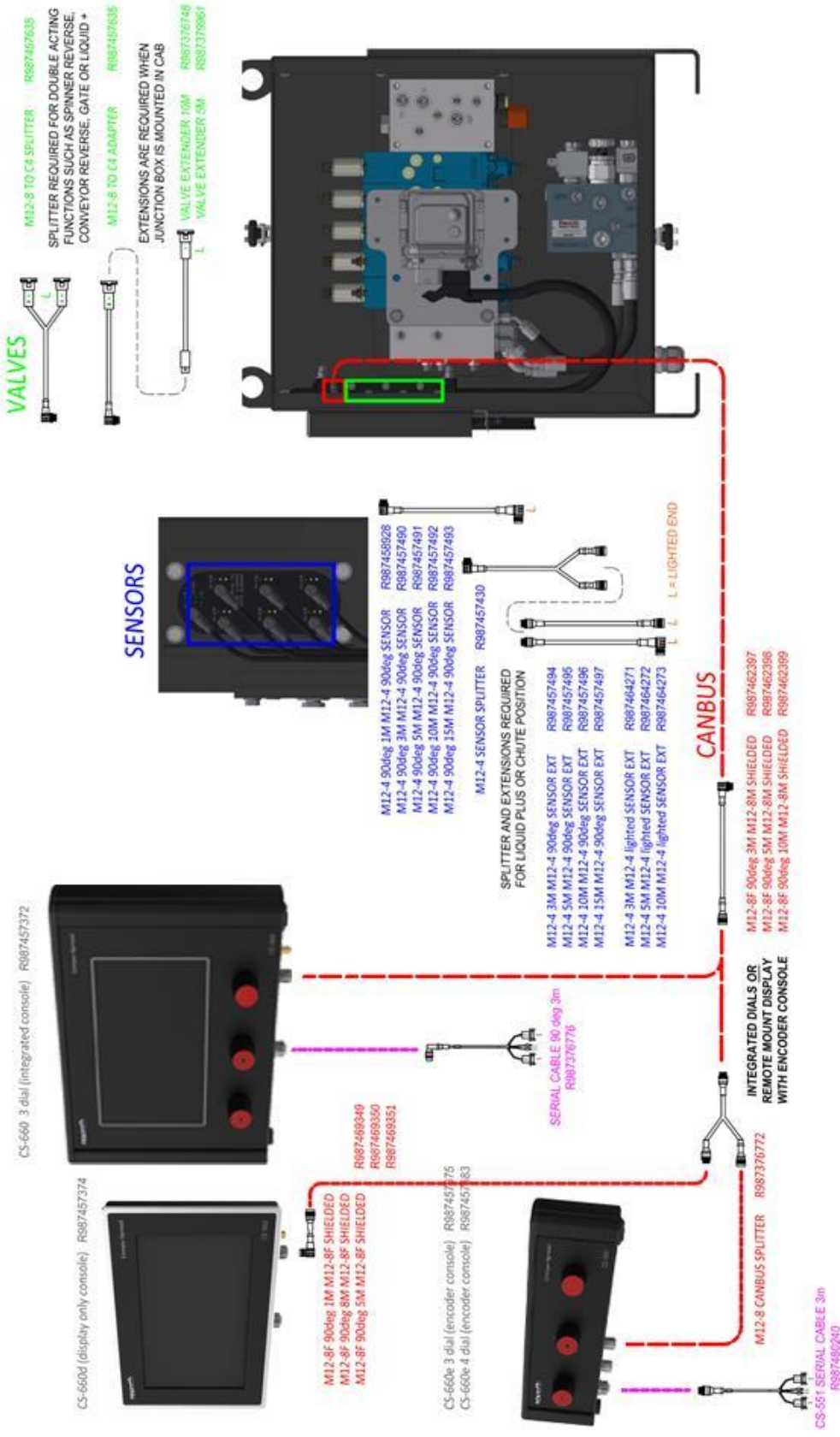
Note: Failure to maintain proper fuse protection can lead to product damage and fire hazard not covered by warranty. And failure to follow the recommendations will void your warranty.

6 Installation Test Checklist

Work order #:		Date:
Part number:		Software Version:
Serial number:		Signature:
After all controller cables and hydraulics are plumbed – vehicle hopper empty		
OK		NOTES
<input type="checkbox"/>	Start the vehicle – engage hydraulic pump	
<input type="checkbox"/>	Power on display, check for backlight and display operation	
<input type="checkbox"/>	Press and hold the “speed” field for 5 seconds , press “up arrow” to set a speed– (Turning on simulated ground speed)	
<input type="checkbox"/>	Press the up arrow again to increase speed to 20	
<input type="checkbox"/>	Rotate all the dials clockwise to 5 – rate should change	
<input type="checkbox"/>	Verify that the conveyor/auger is operating – feedback?	
<input type="checkbox"/>	Verify that the spinner is operating	
<input type="checkbox"/>	Verify that the liquid pump is operating – feedback?	
<input type="checkbox"/>	Verify that the gate cylinder and sensor is operating (if equipped)	
<input type="checkbox"/>	Press the speed down arrow to lower the speed to 0 – press the speed field to exit	
<input type="checkbox"/>	Drive the vehicle to check that vehicle speed registers	
<input type="checkbox"/>	Activate the joystick as defined in the OSD test drawing – verify proper actuation	
<input type="checkbox"/>	Test special functions – power float, low oil, emergency raise	
<input type="checkbox"/>	Test auxiliary switches for proper operation	

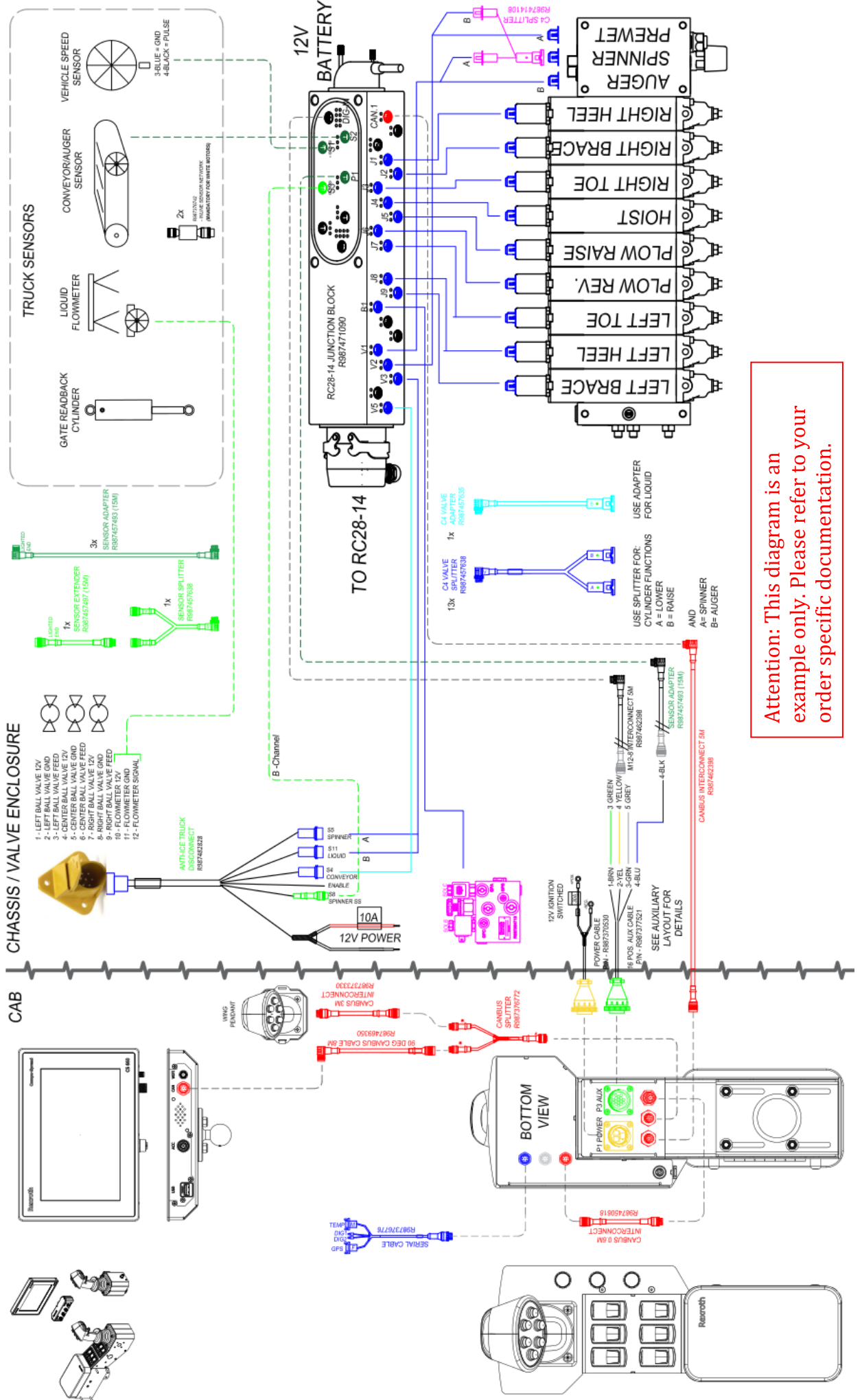
The above procedure is a simple way to verify system connections, hydraulics operation, and sensor feedback. It may not work for all the systems. The reliable way to test is to follow the steps in CS-660 Calibration Manual.

7 Example system layout



Attention: This diagram is an example only. Please refer to your order specific documentation.

8 Example system layout with Joystick Console



Attention: This diagram is an example only. Please refer to your order specific documentation.

9 Cable Connection Chart

RC4-5 Controller

RC4-5 Junction box connectors	Default function (Refer to order specific documentation)	Spinner or conveyor reverse
Sensors		
S1-A	Ground Speed	Ground Speed
S1-B	Spare	Spare
S2-B	Spinner SS	Spinner SS
S2-A	Conveyor Speed	Conveyor Speed
S3-B	Anti-Ice flow /Level	Anti-Ice flow /Level
S3-A	Prewet flow/Level	Prewet flow/Level
Analog Inputs		
A1-A	Configurable	Configurable
A1-B	Configurable	Configurable
A2-A	Gate Position Sensor	Gate Position Sensor
A2-B	Configurable	Configurable
A3-A	Configurable	Configurable
A3-B	Configurable	Configurable
Dig Sensors-8pin		
D1-8	Configurable	Configurable
PWM Outputs		
V1-B	Conveyor output	Conveyor output
V1-A	Spinner output	Conveyor reverse
V2-B	Prewet	Spinner output
V2-A	Anti-Ice	Spinner reverse
Digital Outputs		
V3-B	Configurable, GS12-default	Prewet
V3-A	Configurable, Reverse-default	Anti-Ice
V4-B	Gate Up	Gate Up
V4-A	Gate Down	Gate Down
V5-B	Configurable	(Dig Option 3)
V5-A	LEDop(50mA)	LEDop(50mA)

Attention: This chart is an example only. Please refer to your order specific documentation (OSD).

10 Cable Connection Chart with Joystick Console

RC28-14 Controller

<u>Junction box connectors</u>	<u>Junction box connectors</u>	<u>Spinner or conveyor reverse</u>
<u>Sensors</u>		
<u>S1-A</u>	<u>Ground Speed</u>	<u>Ground Speed</u>
<u>S1-B</u>	<u>Spare</u>	<u>Spare</u>
<u>S2-A</u>	<u>Conveyor Speed</u>	<u>Conveyor Speed</u>
<u>S2-B</u>	<u>Spinner Speed</u>	<u>Spinner Speed</u>
<u>S3-A</u>	<u>Prewet flow/Level</u>	<u>Prewet flow/Level</u>
<u>S3-B</u>	<u>Anti-Ice flow/Level</u>	<u>Anti-Ice flow/Level</u>
<u>Analog Inputs</u>		
<u>A2-A</u>	<u>Gate Position</u>	<u>Gate Position</u>
<u>A2-B</u>	<u>Configurable</u>	<u>Configurable</u>
<u>A1-B</u>	<u>Configurable</u>	<u>Configurable</u>
<u>A1-A</u>	<u>Configurable</u>	<u>Configurable</u>
<u>A3-A</u>	<u>Configurable</u>	<u>Configurable</u>
<u>A3-B</u>	<u>Configurable</u>	<u>Configurable</u>
<u>Digital Inputs</u>		
<u>D1-8</u>	<u>Configurable</u>	<u>Material detect</u>
<u>Prox Inputs</u>		
<u>P1-A</u>	<u>Prox1</u>	<u>Prox1</u>
<u>P1-B</u>	<u>Prox2</u>	<u>Prox2</u>
<u>PWM Outputs</u>		
<u>V1-B</u>	<u>Conveyor output</u>	<u>Conveyor output</u>
<u>V1-A</u>	<u>Spinner output</u>	<u>Conveyor reverse</u>
<u>V2-B</u>	<u>Prewet</u>	<u>Spinner output</u>
<u>V2-A</u>	<u>Anti-Ice</u>	<u>Spinner reverse</u>
<u>V3-B</u>	<u>Configurable, GS12-default</u>	<u>Prewet output</u>
<u>V3-A</u>	<u>Configurable, Reverse-default</u>	<u>Anti-Ice</u>
<u>V4-B</u>	<u>Gate Up</u>	<u>Gate Up</u>
<u>V4-A</u>	<u>Gate Down</u>	<u>Gate Down</u>
<u>V5-B</u>	<u>C-Boom(Dig Option 2)</u>	<u>(Dig Option 2)</u>
<u>V5-A</u>	<u>R-Boom(Dig Option 3)</u>	<u>(Dig Option 3)</u>
<u>Joystick Function Outputs</u>		
<u>J1</u>	<u>1A,1B</u>	<u>1A,1B</u>

Attention: This chart is an example only. Please refer to your order specific documentation.

J2	2A,2B	2A,2B
J3	3A,3B	3A,3B
J4	4A,4B	4A,4B
J5	5A,5B	5A,5B
J6	6A,6B	6A,6B
J7	7A,7B	7A,7B
J8	8A,8B	8A,8B
J9	9A-AUX 1.9B-AUX 2	9A-AUX 1.9B-AUX 2

Power Float Outputs

B1-A	Float_1(2.2A)	Float_1(2.2A)
B1-B	Float_1(2.2A)	Float_1(2.2A)
B2-A	Float_2(2.2A)	Float_2(2.2A)
B2-B	Float_2(2.2A)	Float_2(2.2A)
B3-A	OIL/PTO(2.2A)	OIL/PTO(2.2A)
B3-B	AUX(2.2A)	AUX(2.2A)

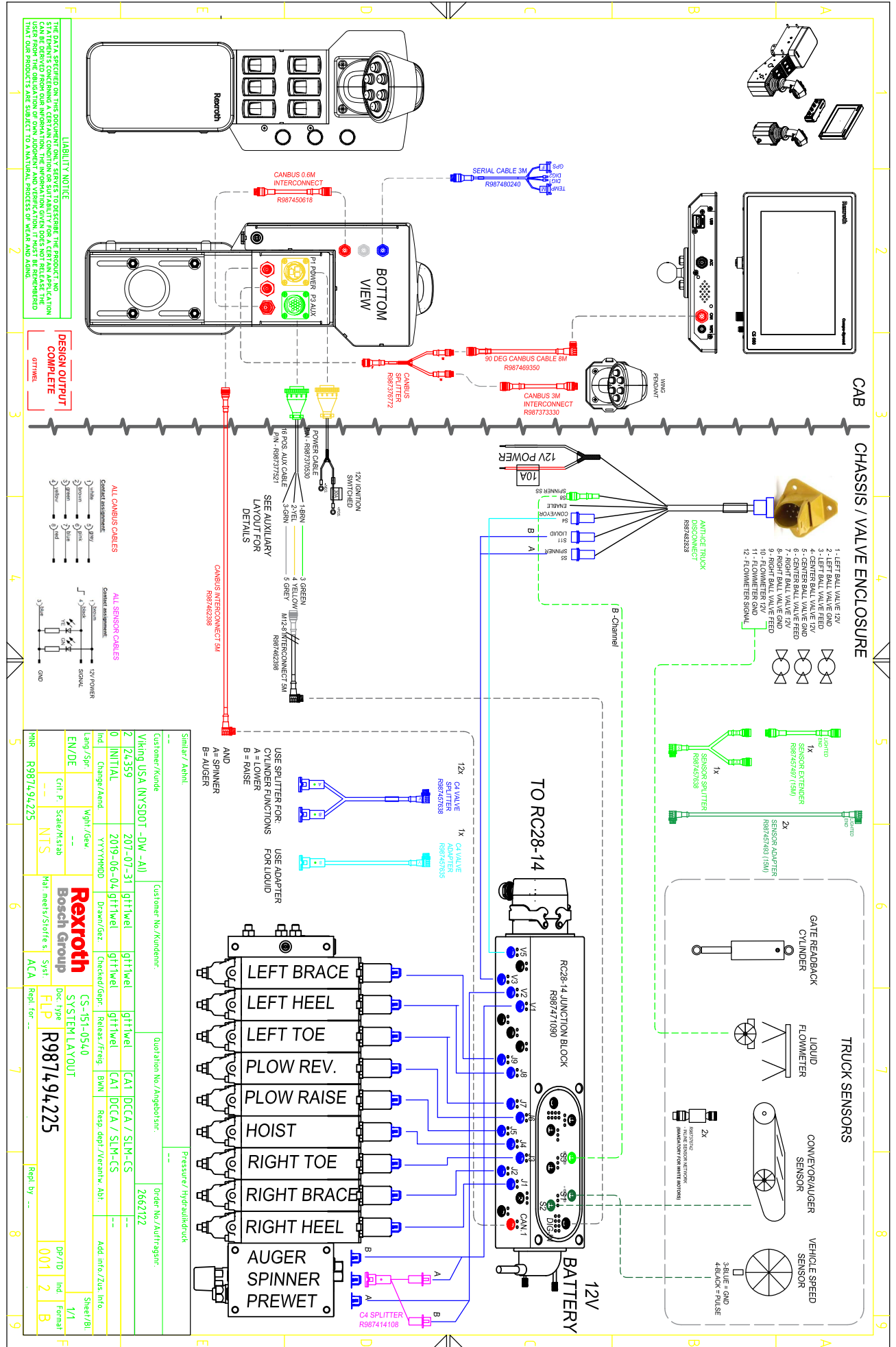
Light/Dig Outputs

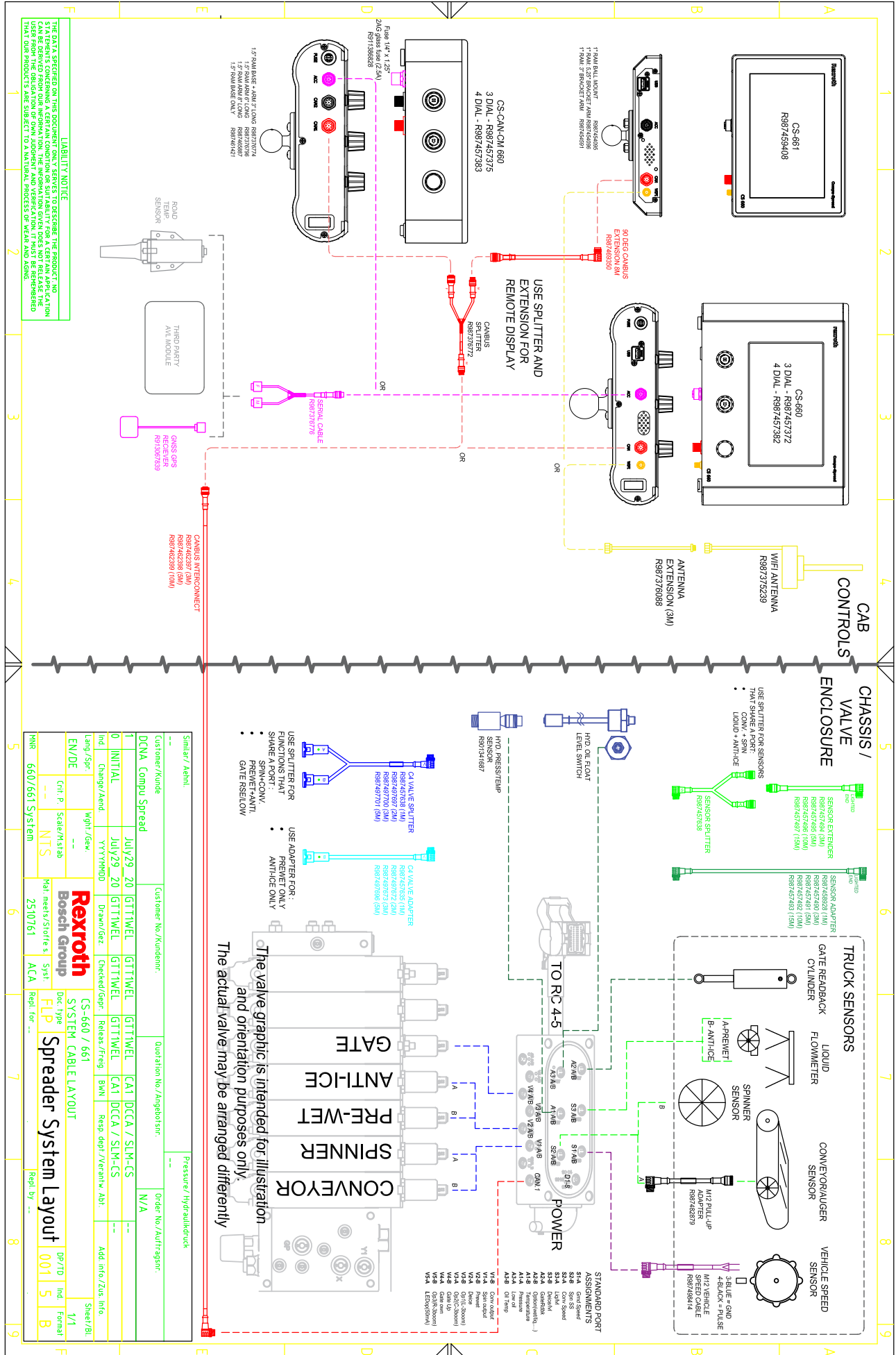
L1-L8	For future use	For future use

Attention: This chart is an example only. Please refer to your order specific documentation.

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Customer/Article	DCNA Compu Spread		Customer No./Auftrag-Nr.	Quotation No./Angebots-Nr.	Order No./Auftrags-Nr.
INITIAL	JULY29	20	GTTWEL	GTTWEL	[CA1] DCCA / SIM-CS
Change/Änd.	YYYYMMDD		GTTWEL	GTTWEL	[CA1] DCCA / SIM-CS
Lang./Spr.	Wght./Gew.		Checked	Released	Revis. dep./Veränd. Abt.
EN/DE	Chr. P.	Scale/1:1/1:2	Bosch Rexroth System Cable Layout 001 5 B		
MNR	660/661	System			
Pressure/Hydrauldruck			Repl. for		
Sheet/Bl.	1/1		Repl. by		

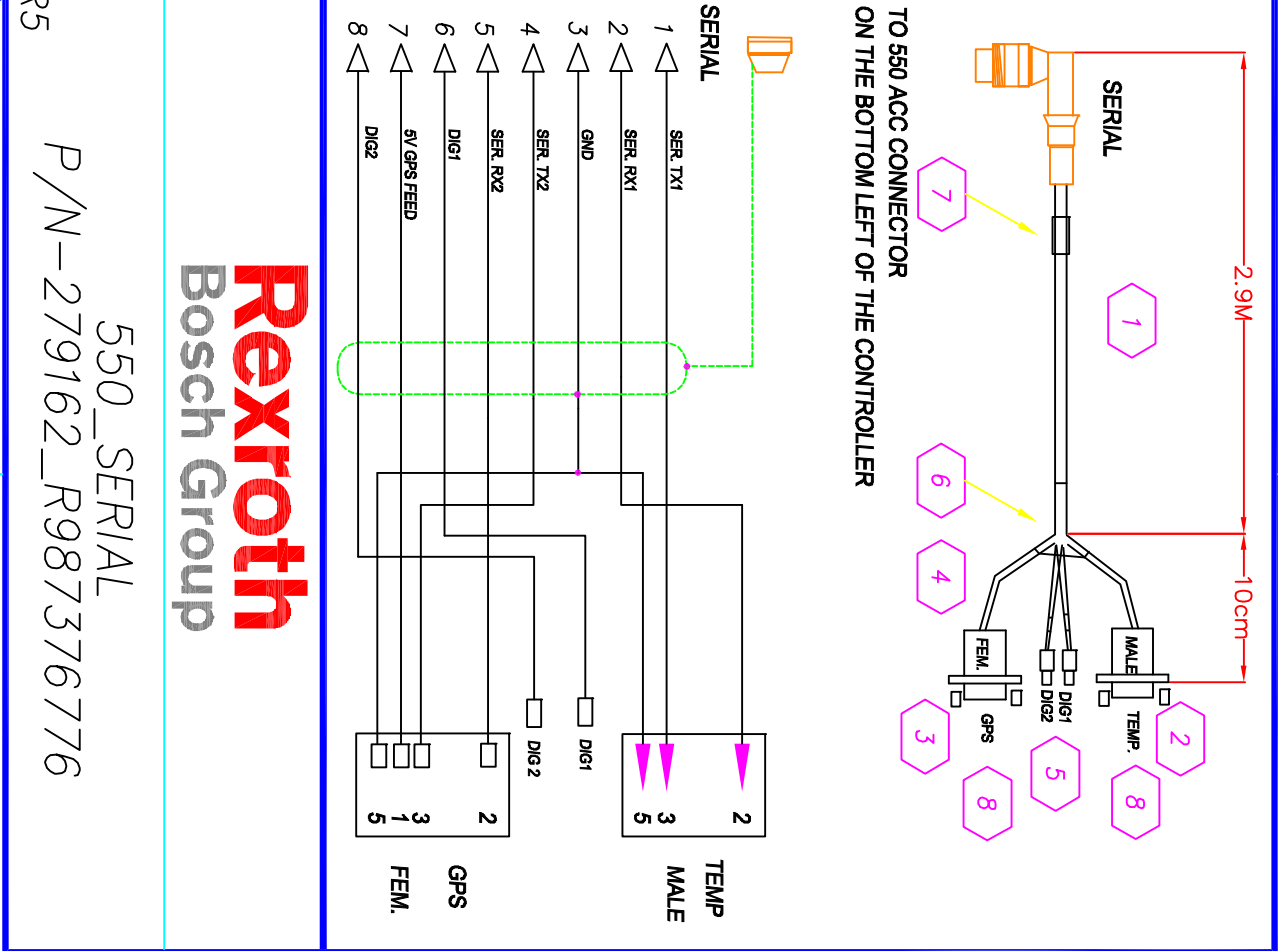
The valve graphic is intended for illustration and orientation purposes only. The actual valve may be arranged differently.

STANDARD PORT ASSIGNMENTS

A1	Spool
A2	Spool
A3	Spool
A4	Spool
B1	Spool
B2	Spool
B3	Spool
B4	Spool
C1	Spool
C2	Spool
C3	Spool
C4	Spool
D1	Spool
D2	Spool
D3	Spool
D4	Spool
E1	Spool
E2	Spool
E3	Spool
E4	Spool
F1	Spool
F2	Spool
F3	Spool
F4	Spool
G1	Spool
G2	Spool
G3	Spool
G4	Spool
H1	Spool
H2	Spool
H3	Spool
H4	Spool
I1	Spool
I2	Spool
I3	Spool
I4	Spool
J1	Spool
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W4	Spool
X1	Spool
X2	Spool
X3	Spool
X4	Spool
Y1	Spool
Y2	Spool
Y3	Spool
Y4	Spool
Z1	Spool
Z2	Spool
Z3	Spool
Z4	Spool

BILL OF MATERIAL

ITEM	QTY.	DESCRIPTION
1	1	MALE. M12 8 POS. 90deg 3M- CONEC P/N- 43-18885
2	1	DB-9 MALE - AMP P/N - 747043-4
3	1	DB-9 FEMALE - AMP P/N - 747318-4
4	5	LABEL LEG AS PER DRAWING
5	2	1/4" FEMALE QC
6	AS REQ.	ADHEASIVE HEATSHRINK
7	1	LABEL: 550 SERIAL P/N R987376776, DATE, TESTED
8	4	COUPLING NUT: DIGI-KEY - 160-000-006R032 THREAD NUTS ONTO LOCKING SCREWS
	R6	COUPLING NUT: DIGI-KEY - 160-000-006R032



DRAWN BY: T.G FEB_1/10 SHEET SIZE: A

CHECKED BY: T.G MAR_8_11

DESIGN ENG.: T.G FEB_1/10 REV.: 6

CUSTOMER: BOSCH
REXROTH

SCALE: SCALE DRAWING NO.: R987376776_R5



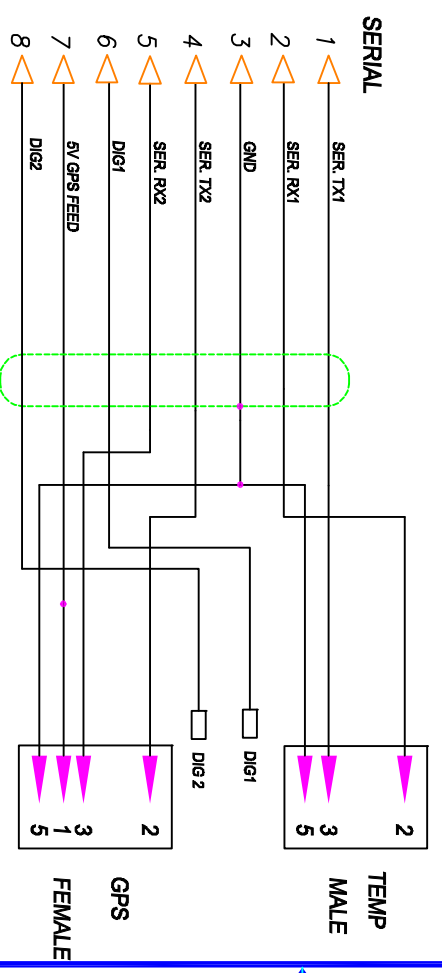
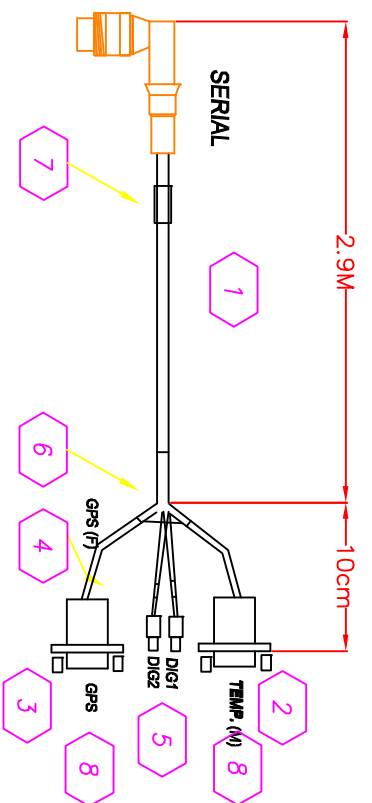
550_SERIAL
P/N-279162_R987376776

4 3 2 1

BILL OF MATERIAL

ITEM	QTY.	DESCRIPTION
1	1	MALE. M12 8 POS. 3M 90deg- CONEC P/N- 43-18885
2	1	DB-9 MALE - AMP P/N - 747043-4
3	1	DB-9 FEMALE - AMP P/N - 747318-4
4	5	LABEL LEG AS PER DRAWING
5	2	1/4" FEMALE QC
6	AS REQ.	ADHEASIVE HEATSHRINK
7	1	LABEL:550 SERIAL(NULL) P/N R987400008, DATE, TESTED
8	4	COUPLING NUT: DIGI-KEY - 160-000-006R032
		THREAD NUTS ONTO LOCKING SCREWS
		SIMILAR TO 279162-PINS 2, 3 SWAPPED ON GPS LEAD
		R5 CONEC TINNED

DRAWN BY: T.G	AUG22/12	SHEET SIZE: A
CHECKED BY: T.G	AUG22/12	REV.: 5
DESIGN ENG.: T.G	AUG22/12	
CUSTOMER: BOSCH REXROTH		
SCALE: SCALE	DRAWING NO.: R987400008	



Rexroth
Bosch Group

550_SERIAL_NULL
P/N-R987400008

4

3

2

1

4

3

2

1

A

B

C

D

A

B

C

D